Appl. No. 09/773,665 Reply to Office Action of: May 16, 2006

Amendments to the Claims

This listing of claims will replace all prior versions and listings of claims in the application:

<u>Listing of claims:</u>

1 - 11. (cancelled)

- 12. (currently amended) A method for verifying a signature for a message m in a data communication system established between a sender and a recipient verifier, said sender generating having generated in a secure computer system a masked signature components (r, s, e), where having a first signature component r is an integer derived from a coordinate of computed using a first short term public key [[kP,]] derived from a first short term private key; a second signature component s is a signature component derived by binding computed using a second short term private key[[, the]] on said message m_s and short and long term private keys, and a long term private key, and said first signature component r; and a third signature component r is a second signature component obtained by combining computed using said first and second short term private keys, said method for verifying comprising the steps of a said verifier:
 - a) obtaining a pair of signature components (\bar{s}, r) , said component \bar{s} being derived from said first and second signature components generated by a signor a regular signature derived from said masked signature (r, s, c), said regular signature having said first signature component r, and another signature component \bar{s} computed using said second signature component s and said third signature component s;
 - b) recovering a coordinate pair (x_1,y_1) corresponding to said first short term public key-kP using said pair (\bar{s},r) and point on an elliptic curve defined over a finite field using said message m and said another signature component \bar{s} ;
 - c) converting an element of said point to an integer;

 [[c)]]d) calculating a signature component value r' from one of said coordinate pair using said integer; and

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[[d)]]e) verifying said regular signature (r,\bar{s}) if said value r' [[=]] is equal to said first signature component r.

- 13. (currently amended) A method according to claim 12 further comprising the step of said verifier receiving said masked signature (r, s, c) from said signor sender and converting (s, r, c) (r, s, c) to obtain said pair (\bar{s}, r) regular signature (r, \bar{s}) .
- 14. (currently amended) A method according to claim 12 further comprising the step of said signor sender converting said masked signature (s, r, c) (r, s, c) to said pair (\bar{s}, r) regular signature (r, \bar{s}) and said signor sender sending said pair (\bar{s}, r) regular signature (r, \bar{s}) to said verifier.
- 15. (currently amended) A method according to claim 12 wherein said coordinate pair (x_1, y_1) point is calculated using a pair of values u and v, said values u and v derived from said pair (\overline{s}, r) regular signature (r, \overline{s}) and said message m.
- 16. (currently amended) A method according to claim 15 wherein said coordinate pair (x_1, y_1) point is calculated as $(x_1, y_1) = uP + vQ$, wherein P is a point on an elliptic curve E and Q is a public verification key of said signor sender derived from P as Q = dP.
- 17. (previously presented) A method according to claim 15 wherein said value u is computed as $u = \overline{s}^{-1}e \mod n$ and said value v is computed as $v = \overline{s}^{-1}r \mod n$, e being a representation of said message m.
- 18. (currently amended) A method according to claim 17 wherein e is calculated as e = H(m), H() being a hash function of said signor sender and being known to said verifier.
- 19. (currently amended) A method according to claim 12 wherein [[said]] a coordinate x_1 of said point is first converted to an integer \bar{x}_1 prior to calculating said component r'.

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- 20. (previously presented) A method according to claim 19 wherein said component r' is calculated as $r' = \bar{x}_1 \mod n$.
- 21. (currently amended) A method according to claim 12 wherein prior to calculating said component r', [[said]] a coordinate pair (x_1,y_1) of said point is first verified, whereby if said coordinate pair (x_1,y_1) is a point at infinity, then said regular signature (r,\bar{s}) is rejected.